

ACTE: Individual/Group Robotics B Rubric

DIRECTIONS

- 1. Ask the student/group for the **printed portfolio**. Digital or electronic portfolios are not accepted. Allow no more than 5 minutes for project setup and score the printed portfolio during setup.
- 2. Robotics B evaluates both the **engineering/build process** and student-created **drag-and-drop/block or written programming**. A purchased kit is permitted, but judges must distinguish a predesigned build from original design, modification, and creative engineering. Confirm that the robot design, build decisions, programming, and documentation are student-created. **AI-generated designs, code, or production assets are prohibited**. If suspected or disclosed, pause scoring and refer the entry to ACTE staff.
- 3. Allow no more than 10 minutes for the project presentation. The student may choose which portion of a larger body of work to show.
- 4. Judges may ask questions for no more than 5 minutes and are not limited to the topics listed in the rubric.
- 5. Enter a score for every criterion. Add the /30 portfolio score and /70 project/presentation score for the /100 final score, then initial page 2.

PRINTED PORTFOLIO CHECKLIST			Points
Online Orientation Certificate	0 Certificate is missing.	10 Certificate is printed and placed as page 1 of the portfolio.	
Printed Portfolio	0 No printed portfolio is submitted, or only a digital/electronic portfolio is provided.	10 A complete printed portfolio is submitted at judging. Digital portfolios are not accepted.	
Required Portfolio Sections	0 Required printed portfolio sections are not provided.	10 - Printed portfolio includes these 9 sections: 1. Online Orientation Certificate (first page) 2. Project identification page: student name(s), school, category, level, and region 3. Table of contents 4. Project narrative: purpose, learning, and benefit 5. Software and hardware used 6. Problem/challenge statement, criteria and constraints, research, kit/source identification, concept sketches, design options, selected design, diagrams, parts list, build plan, and programming plan 7. Build-stage photographs, modifications from the kit design, representative block or written code, test procedures/data, failures, debugging notes, redesigns, revisions, and final-performance evidence 8. Works cited/bibliography and credits for kit instructions, sample designs, code libraries, tutorials, media, datasets, and other sources 9. Signed statement that the robot design/build decisions, programming, documentation, and production assets are student-created and contain no AI-generated content or assets	
Judges Printed Portfolio Checklist Score			/30

This section is valued at 30 points total.

ROBOTICS B PROJECT & ORAL PRESENTATION RUBRIC

Select the score range that best matches the demonstrated level. Enter one numeric score from 0-10 for each criterion.

PROJECT					Points
Engineering Problem, Criteria & Design Process					
0 No identifiable problem, criteria, constraints, research, design plan, or engineering process.	1-3 Problem and requirements are unclear; little evidence of research, planning, or design-process steps is provided.	4-6 A basic problem and plan are evident, but criteria, constraints, options, rationale, or documentation is incomplete.	7-9 Clear problem, criteria, constraints, research, design options, reasoned selection, and build/program plan are documented.	10 Exceptional process defines the problem, compares alternatives, justifies decisions, and documents a purposeful original solution.	
PROJECT					Points
Robot Design, Construction, Creativity & Customization					
0 No completed robot or construction evidence can be evaluated.	1-3 Robot follows a purchased kit or predesigned model with minimal student modification, creativity, or build understanding.	4-6 Robot is competently assembled from a kit with limited original changes; construction quality or customization is uneven.	7-9 Well-built robot uses purposeful original modifications, component choices, layout, mechanisms, or structure to improve the design.	10 Highly original robot transforms kit components or uses a student-created design with exceptional creativity, craftsmanship, and function.	
PROJECT					Points
Programming Logic, Control & System Integration					
0 No functioning student-created block or written program is provided.	1-3 Programming is mostly prebuilt, copied without understanding, incomplete, or poorly integrated with the robot.	4-6 Student-created code controls basic functions, but logic, organization, motors/sensors, calibration, or integration is uneven.	7-9 Well-organized block or written code uses effective logic, controls, motors/sensors, and calibration to integrate the robot.	10 Exceptional programming shows advanced logic, maintainability, precise control, strong sensor integration, efficiency, and autonomy.	
PROJECT					Points
Testing, Iteration, Task Performance & Reliability					
0 The robot does not perform the task or no testing evidence is provided.	1-3 Major design or programming failures prevent task completion; testing is informal with little documented redesign or debugging.	4-6 Robot completes part or most of the task, but test procedures, data, repeatability, redesign, debugging, or reliability is inconsistent.	7-9 Robot reliably completes the task with documented tests, data, failures, debugging, redesigns, and minor performance issues.	10 Robot performs autonomously and consistently; rigorous test data drives effective build/code iterations, optimization, and reliability.	
PROJECT					Points
Originality, Process Evidence & Student Authorship					
0 Originality, design process, or student authorship cannot be established.	1-3 Work shows limited original decisions; kit design, copied code, sources, build stages, or student contribution are unclear.	4-6 Student contribution is evident, but originality, process evidence, customization, source credits, or technical decisions are basic.	7-9 Original robot and program show clear ownership, appropriate credits, and strong evidence of planning, building, testing, and revision.	10 Distinctive engineering and programming solution proves independent authorship and understanding of major design and code decisions.	
PRESENTATION					Points
Explanation of Engineering & Programming Process					
0 Does not explain or demonstrate the robot, build, program, or design process.	1-3 Explanation is difficult to follow; limited preparation or understanding of how the robot was designed, built, and programmed.	4-6 Explains major build and programming steps, but detail, organization, testing, iteration, or delivery is inconsistent.	7-9 Clearly explains the problem, design options, kit/custom choices, construction, code, test data, failures, redesigns, and performance.	10 Confident demonstration shows command of the engineering-design and programming workflow and justifies major decisions.	
QUESTIONS					Points
Engineering Knowledge, Troubleshooting & Responses					
0 Does not answer judges' questions.	1-3 Answers are incomplete or show little understanding of design, components, construction, code, sensors, testing, or failures.	4-6 Answers most questions and describes basic build, programming, testing, or troubleshooting challenges.	7-9 Provides specific, accurate responses about design decisions, kit modifications, mechanics, electronics, code logic, sensors, testing data, safety, and revisions.	10 Insightful responses demonstrate deep engineering and programming knowledge, effective troubleshooting, reflection, and equal group contribution.	

AI-GENERATED ROBOTICS DESIGN OR PROGRAMMING PROHIBITED: Entries may not contain generative-AI-created robot designs, schematics, block sequences, written code, programming logic, flowcharts, documentation, text, images, or other production assets. Judges should not independently penalize suspected use; pause scoring and refer the entry to ACTE staff for review.

Judges Printed Portfolio Checklist Score	/30
Robotics B Project & Oral Presentation Score	/70
Total Project Score	/100
Ranking (ACTE Staff Only)	

Judges Initials: _____